

# **SIMULATION METHODS IN CONFIGURATIONAL THERMODYNAMICS**

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- **MONTE CARLO**
- **Molecular Dynamics**
- **Phase Field Method**

**Monte Carlo methods** are a widely used class of computational algorithms for simulating the behavior of various physical and mathematical systems. They are distinguished from other simulation methods (such as molecular dynamics) by being **stochastic**, that is nondeterministic in some manner - usually by using **random numbers** (or more often pseudo-random numbers) - as opposed to deterministic algorithms. Because of the repetition of algorithms and the large number of calculations involved, Monte Carlo is **a method suited to calculation using a computer**, utilizing many techniques of computer simulation.

Statistical Physics dealing with macroscopic systems often composed of a number of components comparable to Avogadro's number appeared an important beneficiary of new computer facilities.

A macrosystem may be found in one of its *macroscopic* states determined by particular *microscopic* states  $\{\sigma\}$  of all the components and classically represented by points in a  $6N$ -dimensional phase space ( $N$  is the number of system components).

The macroscopic states characterised by *macroscopic parameters* (observables  $A$ ) such as *energy, volume, degree of chemical order, magnetisation* etc. are usually highly degenerate with respect to the microscopic ones  $\{\sigma\}$ . The values of observables  $A$  measured in particular conditions (temperature, pressure, external field etc.) are identified with corresponding averages  $\langle A \rangle$  over all microscopic states  $\{\sigma\}$  in which the system may be found in this conditions.

The central problem of statistical physics (statistical thermodynamics) is a calculation of the values of  $\langle A \rangle$ . The averaging is performed over an appropriate ensemble of macroscopic systems representing the related microscopic states. An ensemble is characterised by so called density  $\rho(\sigma)$  defined in the way that

$$P(\sigma) = \frac{\rho(\sigma)}{\sum_{\sigma} \rho(\sigma)}$$

is a probability that a system in the ensemble is in the microscopic state  $\sigma$  (see e.g. Huang, 1963).

The principle achievement of the founders of statistical physics was the derivation of formulae for the densities  $\rho_{eq}(\sigma)$  corresponding to ensembles of systems in equilibrium state.

Complete description of the system thermodynamics is derivable from the sum

$$Z = \sum_{\sigma} \rho_{eq}(\sigma)$$

called a **partition function**

Type of ensemble	Usage	Density function $\rho_{eq}$ , $H$ denotes Hamiltonian of the system
Microcanonical ensemble	Isolated systems with fixed energy $E$	$\delta_{H(\{\sigma_i\}), E}$
Canonical ensemble	Systems with fixed volume $V$ and number of particles $N$ studied at fixed temperature $T$ determined by thermal bath	$\exp\left[-\frac{H(\{\sigma_i\})}{k_B T}\right]$
Isothermal-Isobaric ensemble	Systems with fixed number of particles $N$ studied at fixed pressure $P$ and temperature $T$ determined by thermal bath	$\exp\left[-\frac{H(\{\sigma_i\}) + PV}{k_B T}\right]$
Grand Canonical ensemble	Opened systems with fixed volume $V$ studied at fixed temperature $T$ determined by thermal bath	$\exp\left[-\frac{H(\{\sigma_i\}) + \sum_k N_k \mu_k(\{\sigma_i\})}{k_B T}\right]$ $\mu_k$ – chemical potential

# SAMPLING

If  $A(\sigma)$  denotes the value of the observable  $A$  in the microscopic state  $\sigma$  then:

$$\langle A \rangle = \sum_{\sigma} [P(\sigma) \times A(\sigma)] = \frac{1}{Z} \sum_{\sigma} [\rho(\sigma) \times A(\sigma)] \quad \star$$

where the sum covers all possible microscopic states  $\sigma$  (whose number is most often extremely large or even infinite) and its strict calculation is usually unfeasible. The basic idea is to approximate the complete sum ( $\star$ ) by a partial one performed over some subset  $\{\sigma_i, i = 1, \dots, M\}$  of the microscopic states  $\sigma$

$$\langle A \rangle \approx \frac{\sum_{i=1}^M [\rho(\sigma_i) \times A(\sigma_i)]}{\sum_{k=1}^M \rho(\sigma_k)} \quad \star \star$$

**Simple sampling:** the random choice of the states  $\sigma_i$  runs according to a uniform distribution. **Drawback:** many  $\sigma_i$  states may correspond to the low value of the density  $\rho$  making the approximation poor.

**Importance sampling:** the states  $\sigma_i$  are randomly chosen with a non-uniform distribution  $\Pi(\sigma)$  :

$$\langle A \rangle \approx \frac{\sum_{i=1}^M [\rho(\sigma_i) \times A(\sigma_i) \times \Pi^{-1}(\sigma_i)]}{\sum_{k=1}^M [\rho(\sigma_k) \times \Pi^{-1}(\sigma_k)]}$$

If  $\Pi(\sigma) = P(\sigma) = \frac{\rho(\sigma)}{\sum_{\sigma} \rho(\sigma)}$  then  $\langle A \rangle = \frac{1}{M} \sum_{i=1}^M A(\sigma_i)$

**Problem:** how to generate a set of microstates with the desired distribution ??

# Markov chains as a tool for importance sampling

Probability that an event  $y_n$  occurs at a time  $t_n$  in condition that events  $y_1, y_2, \dots$  occurred at times  $t_1, t_2, \dots$

  $P_{1|n-1}(y_n, t_n | y_1, t_1; \dots y_{n-1}, t_{n-1})$

Markov chain of events:

$$P_{1|n-1}(y_n, t_n | y_1, t_1; \dots y_{n-1}, t_{n-1}) = P_{1|1}(y_n, t_n | y_{n-1}, t_{n-1})$$

If states of the systems in an ensemble change due to Markov processes, the time evolution of the probability distribution  $P(\sigma)$  is given by a **Master equation**:

$$\frac{dP(\sigma_i)}{dt} = -\sum_j W(\sigma_i \rightarrow \sigma_j) \times P(\sigma_i) + \sum_j W(\sigma_j \rightarrow \sigma_i) \times P(\sigma_j)$$

The evolution leads to a stationary distribution  $P_{st}(\sigma)$ :  $\frac{dP_{st}(\sigma_i)}{dt} = 0$  provided that:

$$\sum_j W(\sigma_i \rightarrow \sigma_j) \times P_{st}(\sigma_i) = \sum_j W(\sigma_j \rightarrow \sigma_i) \times P_{st}(\sigma_j)$$

hence: 
$$\frac{W(\sigma_i \rightarrow \sigma_j)}{W(\sigma_j \rightarrow \sigma_i)} = \frac{P_{eq}(\sigma_j)}{P_{eq}(\sigma_i)} = \frac{\rho_{eq}(\sigma_j)}{\rho_{eq}(\sigma_i)}$$
 ← Detailed balance condition for transition frequencies  $W$

The detailed balance guarantees a convergence of a Markov chain to  $P_{eq}(\sigma)$ .

Simulation of **Markov chains** is a typical task realised by means of **Monte Carlo** algorithms:

Stochastics is digitally simulated by random number generators - i.e. computer codes generating with **a uniform probability** numbers from a fixed interval (most often  $\langle 0,1 \rangle$ ).

### Basic idea:

- Let a certain event occur **in reality** with a probability **P**
- Random number  **$R \in \langle 0,1 \rangle$**  is generated
- The event occurs in Monte Carlo simulation **if  $R \in \langle 0,P \rangle$**

# The Monte Carlo method may be basically applied to diverse kinds of problems in statistical physics:

- *Simulation and characterisation of system properties in thermodynamic equilibrium:*

The procedure starts from a system in some (arbitrary) initial state. Subsequently, an evolution of the system is simulated as a Markov chain of microscopic states  $\sigma_i$  with the transition frequencies  $W(\sigma_i \rightarrow \sigma_j)$  obeying detailed balance corresponding to the particular conditions of the equilibrium state in question. The applied algorithm must enable to follow the evolution of some macroscopic parameter of the system (for example its **energy**), so that it is possible to observe the approach of equilibrium (microscopic states are in dynamical equilibrium with the distribution  $P_{eq}(\sigma)$ ). Once this stage is attained, the microscopic states  $\sigma_i$  of the system appearing at particular time moments may be randomly sampled and used in the **averaging procedure** (effectively, time averaging is done).

Example:

$$F = U - T \times S$$



$$U = \frac{1}{M} \sum_{i=1}^M E(\sigma_i)$$

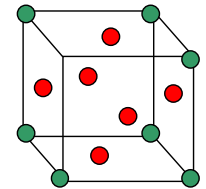
$$S = -k_B \sum_i P(\sigma_i) \times \ln[P(\sigma_i)]$$

$P(\sigma_i)$  is the probability for the occurrence of the microstate  $\sigma_i$ .

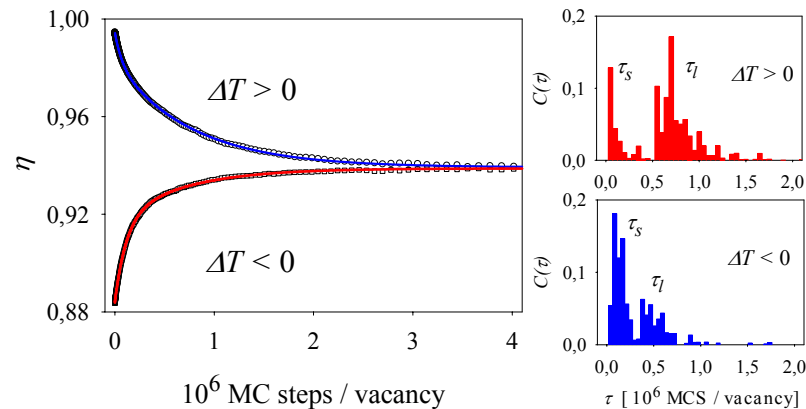
● *Simulation of relaxation processes towards equilibrium:*

The Master equation basically can be regarded as describing relaxation and migration processes. The Monte Carlo method becomes, therefore, a natural tool for simulating such processes. Instead of sampling the microscopic states  $\sigma_i$  after the saturation of the particular Markov chain one now simulates and observes an ensemble of independent parallel Markov chains and performs the averaging of the observable of interest over all of them at particular consecutive time moments also before the saturation. In this way the time evolution (relaxation)  $\langle A \rangle(t)$  of the observable is obtained. Since for a unique choice of transition rates, the condition of detailed balance is not sufficient, the treatment of such problems is, however, sophisticated, involving a number of problems including e.g. the relationship between the computer and real time scales. In general, the relaxation path towards equilibrium can sensitively depend on the particular physical model for the transition rates.

„ORDER-ORDER” RELAXATION



Example



## ● *Simulation of non-equilibrium processes and transport phenomena*

Such processes, as consisting of effective transitions between microscopic states constitute a natural object for studies by means of MC methods. Non equilibrium character of the phenomenon means that **detailed balance must no longer be obeyed** by the transition frequencies which are to model particular microscopic reactions involved in the process.

### Examples:

**Crystal growth** according to the Kossel model. In this model three atomistic-scale processes: deposition, evaporation and diffusion compete. Particular frequency (rate) is modelled and attributed to each process and its selective influence on the overall effect (e.g. crystal growth rate) may then be studied by means of MC.

**Transport phenomena** may be studied by means of MC both in stationary and non-stationary states of the systems simply by monitoring the process of transport during the simulated Markov chain. The standard method consists of monitoring mean-squared displacement  $R_{A(V)}^2(t)$  of a tracer atom (A)/vacancy (V) as a function of MC time.

**Vacancy/tracer diffusion constant  $D_{V(A)}$ :**

$$D_{V(A)} = \lim_{t \rightarrow \infty} \left[ \frac{1}{6N_{V(A)}} \frac{\partial}{\partial t} \left( \sum_{V(A)} R_{V(A)}^2(t) \right) \right]$$

**Correlation factor for atoms A**

$$f_A = \frac{\langle R_A^2(n_A) \rangle}{a^2 \times n_A}$$

# Limitations:

Thermodynamic laws correspond in statistical physics to the **thermodynamic limit**  $N \rightarrow \infty$ , where  $N$  denotes the number of particles in the system. It is obvious that when numerically simulating a system, one always operates with a finite value of  $N$ .

The “simplest” task aiming in the elimination of the parasitic influence of the sample limits on the simulated effects is usually realised by the application of **periodic boundary conditions** consisting of the consideration of the opposite sample boundaries as neighbouring parts. The well-known two-dimensional analogue of this idea is a transformation of a plane into a torus.

Despite compensating the boundary (surface) effects, **periodic boundary conditions cannot remove the finite-size-caused limitation in the consideration of any distance-dependencies**. This applies e.g. to correlation lengths  $\xi$  (which cannot exceed the sample size) and results in **characteristic blunting** (rounding) of singularities marking continuous and discontinuous phase transitions.

# Numerical implementation of MC

(choice of transition frequencies  $W(\sigma_i \rightarrow \sigma_j)$ )

## Classical approach

(Metropolis, N., Rosenbluth, A.W., Rosenbluth, N.N., Teller, A.H., and Teller, E. (1953), *J.Chem.Phys.* 21, 1087)

$$W(\sigma_i \rightarrow \sigma_j) = \begin{cases} \tau^{-1} \times \exp\left[-\frac{\Delta E}{k_B T}\right], & \Delta E > 0 \\ \tau^{-1}, & \Delta E < 0 \end{cases} \equiv \min\left\{\tau^{-1}, \tau^{-1} \times \exp\left[-\frac{\Delta E}{k_B T}\right]\right\}$$

$\Delta E = E_{fin} - E_{ini}$ , system energy equals  $E_{ini}$  in the microstate  $\sigma_i$  and  $E_{fin}$  in the microstate  $\sigma_j$ ;

$k_B$  and  $T$  denote the Boltzmann constant and temperature, respectively and  $\tau$  is a time scale constant

Although the Metropolis transition frequencies obviously fulfil the detailed balance their use may be disadvantageous at high temperatures, where due to the transition probabilities **approaching the value of 1**, the system being off equilibrium keeps oscillating between different microscopic states, which makes the simulated process not perfectly ergodic.

**Glauber algorithm:** (Glauber, R.J., (1963), *J.Math.Phys.* 4, 294)

$$W(\sigma_i \rightarrow \sigma_j) = (\tau)^{-1} \times \frac{\exp\left[-\frac{E_{fin}}{k_B T}\right]}{\exp\left[-\frac{E_{ini}}{k_B T}\right] + \exp\left[-\frac{E_{fin}}{k_B T}\right]} = (\tau)^{-1} \times \frac{\exp\left[-\frac{\Delta E}{k_B T}\right]}{1 + \exp\left[-\frac{\Delta E}{k_B T}\right]}$$

$$W(\sigma_i \rightarrow \sigma_j) \rightarrow \frac{1}{2\tau} \quad (T \rightarrow \infty)$$

$$\forall \Delta E, \quad W(\sigma_i \rightarrow \sigma_j) \leq 1$$

**Probabilistic rationale:**

The probability of an event: "the system either transforms from  $\sigma_i$  to  $\sigma_j$  or remains in  $\sigma_i$ " is in this particular case equal to 1. On the other hand, it must be equal to a sum of the two corresponding probabilities.

The simulation algorithms involving the above formulae for  $\mathcal{W}(\sigma_i \rightarrow \sigma_j)$  work usually in the following cycles:

- The system is in some microscopic state  $\sigma_I$
- Another microscopic state  $\sigma_j \neq \sigma_i$  is chosen at random from the set  $\{\sigma_j\}$
- Transition  $\sigma_i \rightarrow \sigma_j$  is executed or suppressed according to the probability  $\tau \times \mathcal{W}(\sigma_i \rightarrow \sigma_j)$
- Time is incremented by  $\tau$

Drawback:

A number of MC steps are „lost“ - no transition is executed

# „Residence Time“ algorithm:

The basic idea is instead of making a number of unsuccessful attempts to perform a transition; one computes the (average) time for the system to stay in its microstate  $i$ , then performs one of the possible transitions with a choice, which respects the proper weights.

The algorithm works in the following steps:

- All possible transitions  $\sigma_i \rightarrow \sigma_j$  between the microstates of the system are listed and numbered and their corresponding Metropolis frequencies

$$W_k = W(\sigma_i \rightarrow \sigma_j) = \tau^{-1} \times \exp\{-[E(\sigma_j) - E(\sigma_i)]/k_B T\}$$

are determined.

- Two random numbers  $R_1$  and  $R_2$  between 0 and 1 are generated
- The transition  $k$  is chosen and executed (!), for which:

$$\sum_{i=1}^{k-1} \frac{W_i}{\sum_j W_j} < R_1 \leq \sum_{i=1}^k \frac{W_i}{\sum_j W_j}$$

- Time is incremented by:  $\Delta t = -\frac{\ln R_2}{\sum_j W_j}$  ← to be justified in the following

# Problem of time scale

Interpretation of MC simulation results in terms of natural physical phenomena requires that the **MC-time** - i.e. the sequence of simulation steps, is related to **real time**.

A solution of the problem depends on the particular algorithm applied

## Metropolis-type algorithms:

- In each MC step a number **N** of *possible* transitions  $\sigma_i \rightarrow \sigma_j$  has to be determined.
- Each MC step is associated with time increment  $\Delta t = \tau/N$

## „Residence-time“ algorithm

Let the system be in the microstate  $\sigma_i$  at  $t = 0$  and let  $P(t)$  be a probability that it still remains in this microstate at  $t > 0$  ( $t$  is thus the residence time). If  $\{W\}$  denote the frequencies of all possible transitions starting from  $\sigma_i$ , the following differential equation holds:

$$\frac{d}{dt} P(t) = - \left( \sum_i W_i \right) \times P(t)$$

hence:

$$P(t) = C \times \exp \left[ - \left( \sum_i W_i \right) \times t \right] \quad \leftarrow \text{probability distribution for residence times with the normalisation factor } C = \sum_i W_i.$$

and

$$\langle t \rangle = \frac{1}{\sum_i W_i}$$

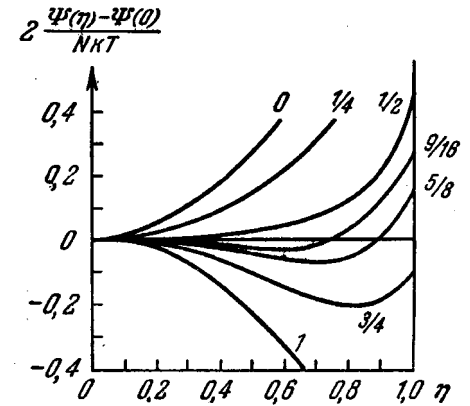
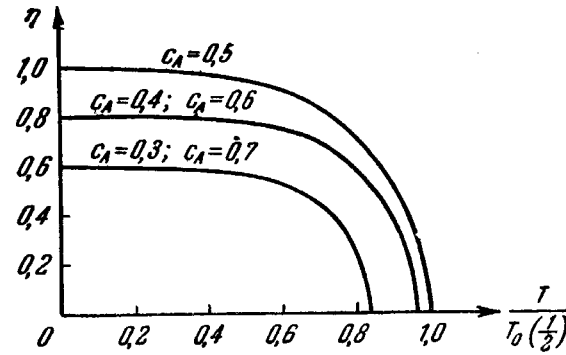
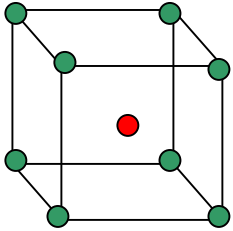
The above is realised numerically by putting:

$$t = - \frac{\ln R_2}{\sum_j W_j}$$

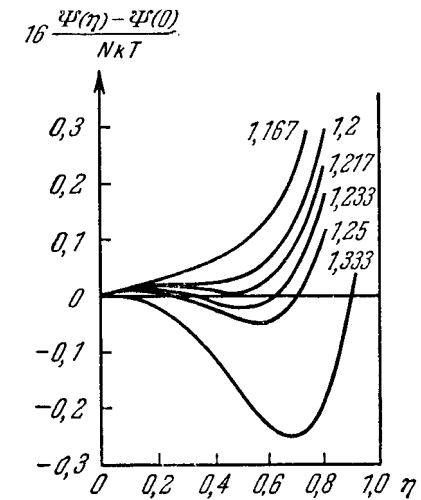
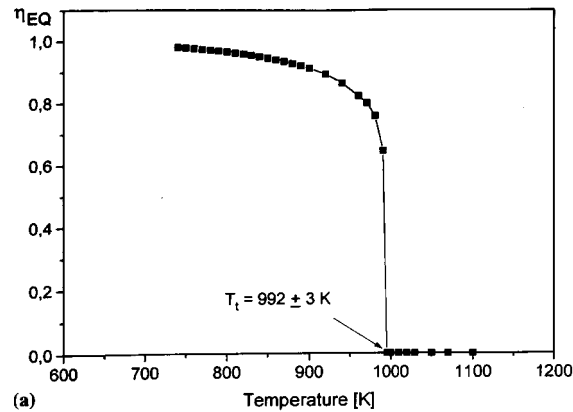
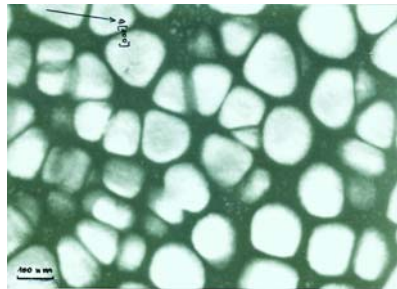
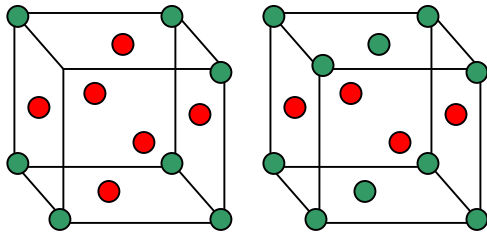
**APPLICATION:**  
**LONG-RANGE ORDERING**  
**IN INTERMETALLICS**

# „Order-disorder” phase transformations

## Continuous (2nd-order) transformation

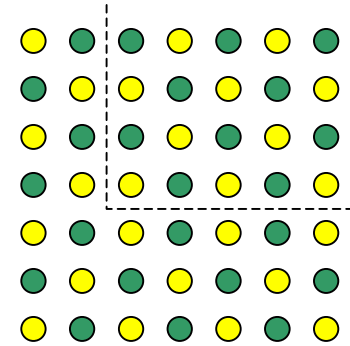
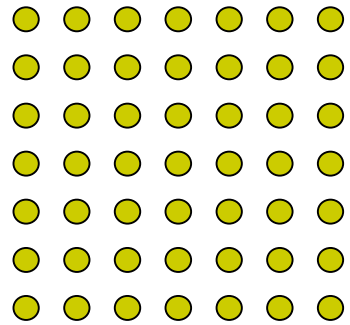
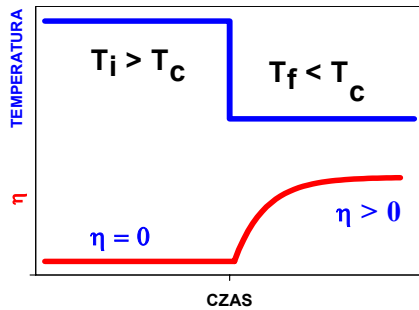


## Discontinuous (1st-order) transformation



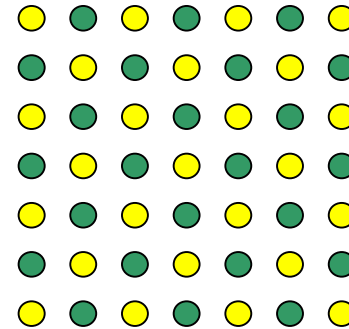
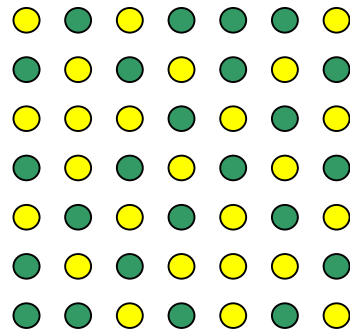
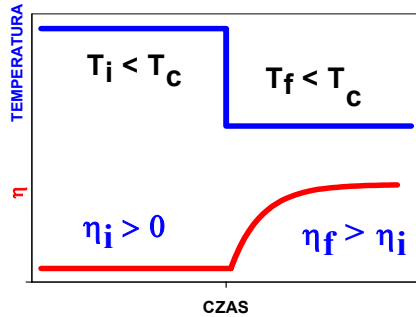
# ORDERING KINETICS

- „Order-disorder” *transformation*

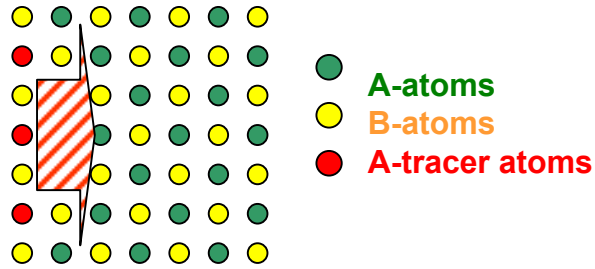


**Antiphase domains**

- „Order-order” *process*



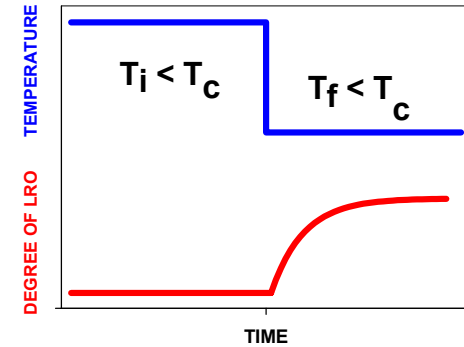
# DIFFUSION



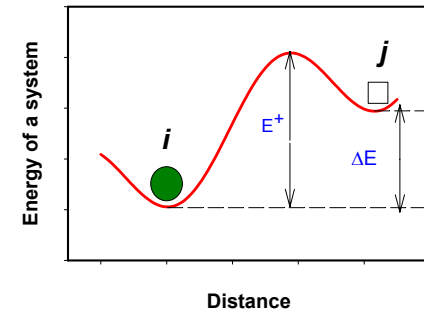
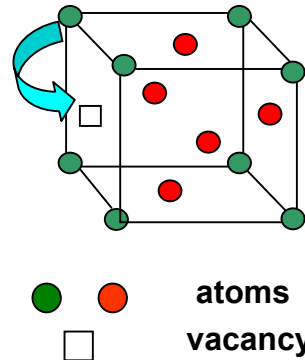
$T = \text{const}$ , degree of LRO = const

# AND in intermetallics

# „ORDER-ORDER”



## COMMON ELEMENTARY MECHANISM: atomic jumps to vacancies



## SPECIFIC FEATURES: correlation of atomic jumps

Minimisation of the energetic cost of local LRO perturbation by jumping atoms:  
„six-jump-cycle”, ASB, triple defect mechanism, antisite diffusion etc.

Formation of equilibrium atomic configuration:  
generation/elimination of antisite defects

**CONSEQUENCE: COMPLEMENTARY INSIGHT INTO ATOMIC JUMP DYNAMICS**

# MONTE CARLO SIMULATIONS:

- **A<sub>3</sub>B** or **AB** binary system with **L1<sub>2</sub>**, **L1<sub>0</sub>** or **B2** superstructure,
- **40 × 40 × 40** cubic cells,
- **1 vacancy (10 vacancies in a piloting study)**

general assumption: vacancy mechanism of atomic migration

Glauber dynamics algorithm:

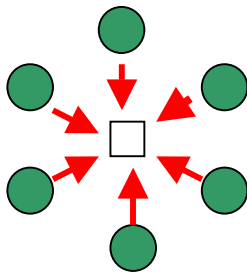
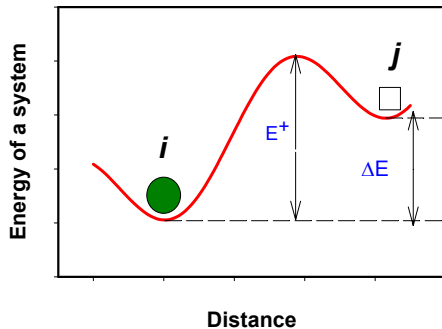
$$w_{i \rightarrow j} = \tau^{-1} \times \frac{\exp\left[-\frac{\Delta E}{kT}\right]}{1 + \exp\left[-\frac{\Delta E}{kT}\right]}$$

„Residence-time“ algorithm:

$$w_i = \Pi_0 \times \exp\left[-\frac{E_i^+ - E_i}{kT}\right]$$

Kinetic Monte Carlo  
KMC

$$\Pi_0 = \left[ \sum_l \exp\left(-\frac{E_l^+ - E_l}{kT}\right) \right]^{-1}, \quad \langle \Delta t \rangle = \frac{\tau}{\Pi_0}$$



## Glauber algorithm:

- ● Random choice of an atom in the 1<sup>st</sup> co-ordination shell of the vacancy.
- ● Execution or rejection of its exchange with the vacancy - according to Glauber probabilities
- ● Repetition of the above steps for each vacancy in the system
- ● Increment of time by  $\tau/Z$ , where  $Z$  is the 1<sup>st</sup> shell co-ordination number

## Residence time algorithm:

- ● Metropolis transition frequencies  $w_j$  ( $j = 1, \dots, Z$ ) are calculated for all potential exchanges of a vacancy with atoms in 1<sup>st</sup> co-ordination shell,
- ● The exchange chosen at random according to the frequencies  $w_j$  is executed,
- ● Time is incremented either by  $\Delta t = -\frac{\ln R}{\sum_j w_j}$  (by generating each time a random fraction  $R$ ), or by an average  $\langle \Delta t \rangle = \frac{1}{\sum_i w_i}$

# Ising-type Hamiltonian:

pair interactions between nn and nnn atoms:

$$E_{Conf} = \sum_{i,k,r} N_{ik}^{(r)} V_{ik}(r)$$

Criteria for pair interaction energy evaluation:

- superstructure stability
- $V_{AA} = \alpha \times V_{BB}$
- no interaction with vacancies

Sources:

**Ni<sub>3</sub>Al:**

DNS (experiment), P.Cenedese et al. J.Phys (France) 50 2193 (1989).

**FePt:**

CE („ab initio”), T. Mohri et al. Mater.Trans. 43 2104 (2002).

# „Embedded Atom Method” (EAM) Hamiltonian

M.S.Daw, M.I.Baskes, *Phys.Rev.B* **29**, 6443, (1984).

The EAM system energy is given by:

$$E = \sum_i F_i(\rho_i) + \frac{1}{2} \sum_{i \neq j} \varphi_{ij}(r_{ij})$$

where  $F_i(\rho_i)$  denotes so-called embedding energy depending on the electron density  $\rho_i$  in the system *without* an atom “ $i$ ” at a position “ $i$ ” and  $\varphi_{ij}(r_{ij})$  is a short-range pair-potential describing the repulsion between cores of “ $i$ ” and “ $j$ ” atoms occupying the positions “ $i$ ” and “ $j$ ” and separated by a distance  $r_{ij}$ .

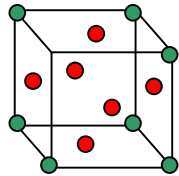
Parameters evaluated by fitting to experimental data – elaborated e.g. for Ni-Al.

# Monitored parameters

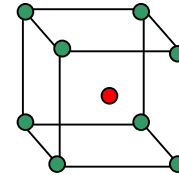
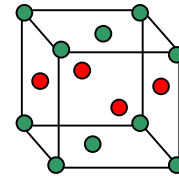
## Atomic Configuration:

### Bragg-Williams-type LRO parameter $\eta$ :

$$\eta = 1 - \frac{N_A^{(B)}}{0.75 \times N^{(B)}}$$



$$\eta = 1 - \frac{N_A^{(B)}}{0.5 \times N^{(B)}}$$



where  $N^{(B)}$  and  $N_A^{(B)}$  denote the number of B-type sublattice sites and the number of A-antisites (A-atoms on the B-sublattice), respectively,

### specific short-range order (SRO) -type parameters APC and NNCOR:

$$APC = \frac{N_{AB}^{(B)(A)}}{N_A^{(B)}}$$

$N_{AB}^{(B)(A)}$  denotes the number of nn pairs of A- and B-antisite atoms.

$$NNCOR_A = \frac{2 \times N_{AA}}{N_A}$$

$N_{AA}$  denotes the number of nn pairs of A-atoms,  $N_A$  is the number of A-atoms

## Atomic Migration:

### “Jump-frequency” parameters:

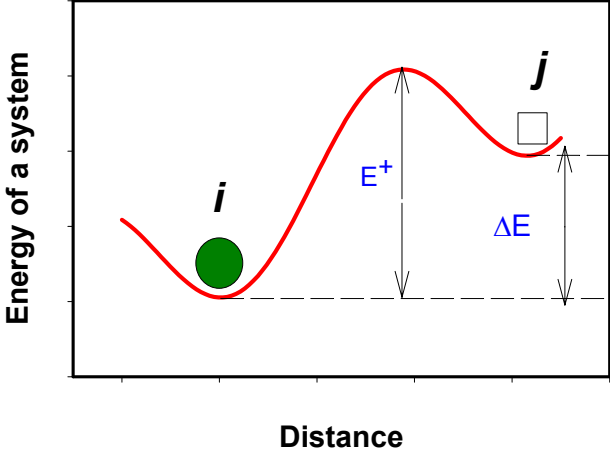
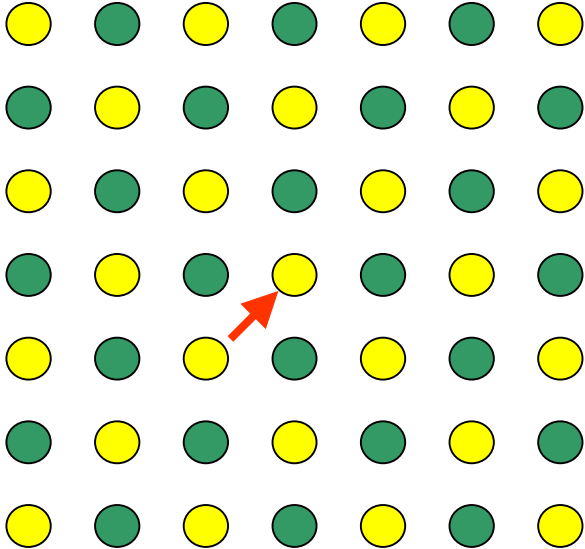
$$P_{A(B):i \rightarrow j} = \frac{N_{A(B):i \rightarrow j}^{exec}}{N_{att}}$$

where:

$N_{A(B):i \rightarrow j}^{exec}$  denotes a number of A(B)-atom jumps from an “i”-type sublattice site to a nn vacancy residing on “j”-type sublattice *executed* within a fixed number of MC steps

$N_{att}$  denotes the total number of *jump attempts* (executed and not executed) during the same MC-time period.

# MOLECULAR STATICS – a tool for saddle-point energy evaluation

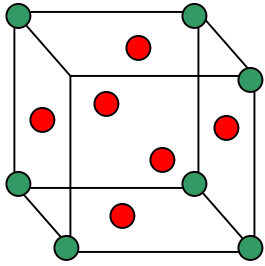


Assumption:

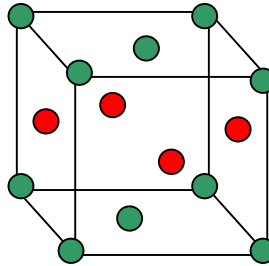
Structural relaxation occurs substantially faster than atomic migration

# RESULTS

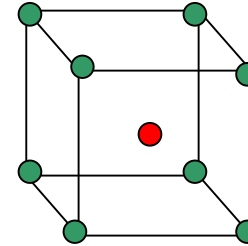
# SUPERSTRUCTURE STABILITY



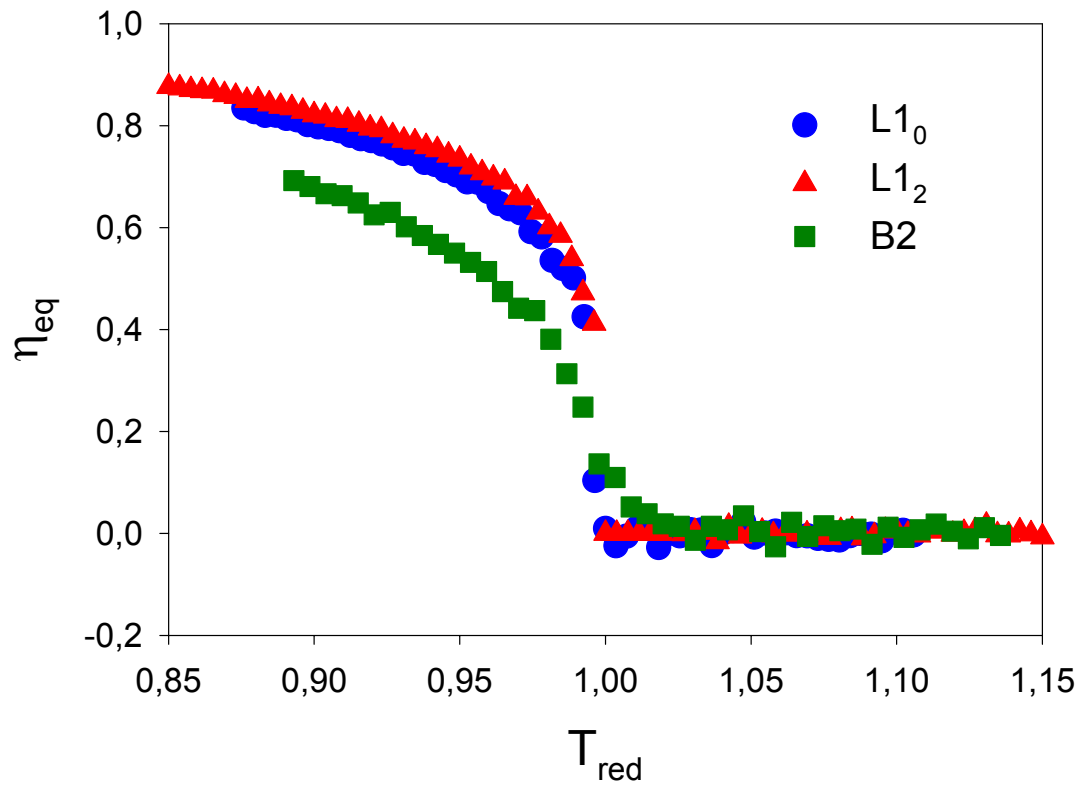
**L1<sub>2</sub>**



**L1<sub>0</sub>**



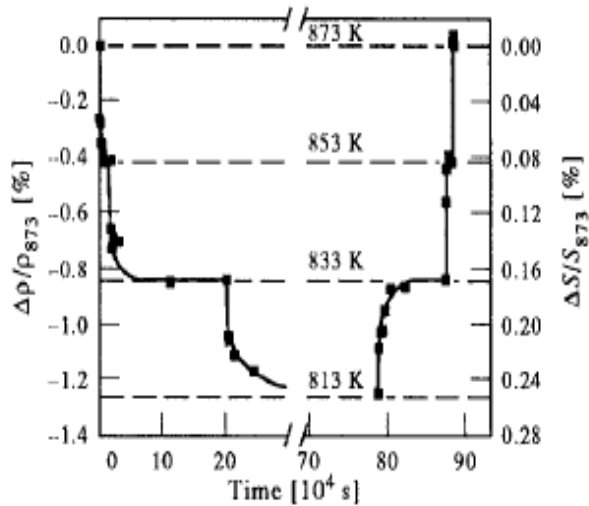
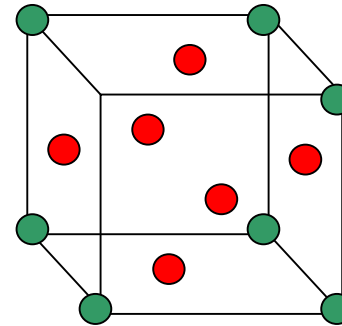
**B2**



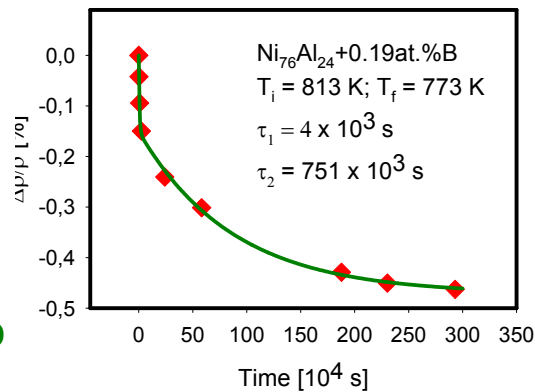
$$T_{red} = \frac{T}{T_{O-D}}$$

# STRUCTURE OF „ORDER-ORDER” RELAXATIONS

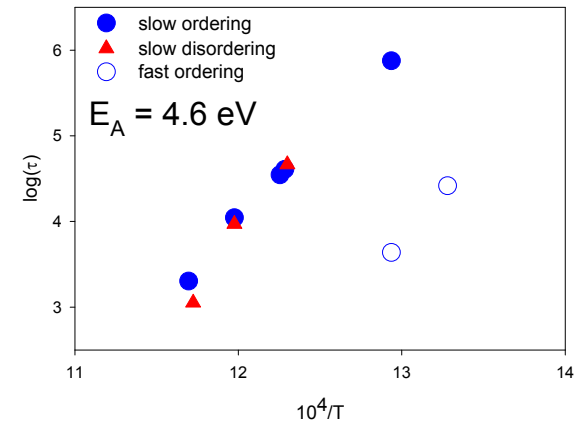
## Ni<sub>3</sub>Al (experiment):



Two time scales showing up at 77 K only



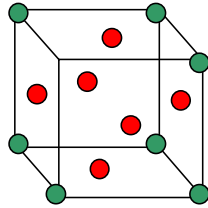
Ni diffusion:  $E_A = 3$  eV



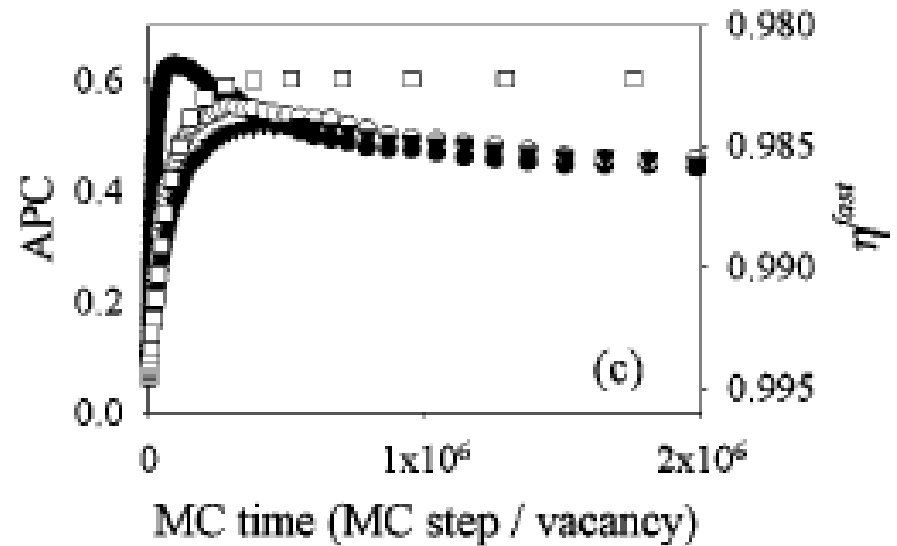
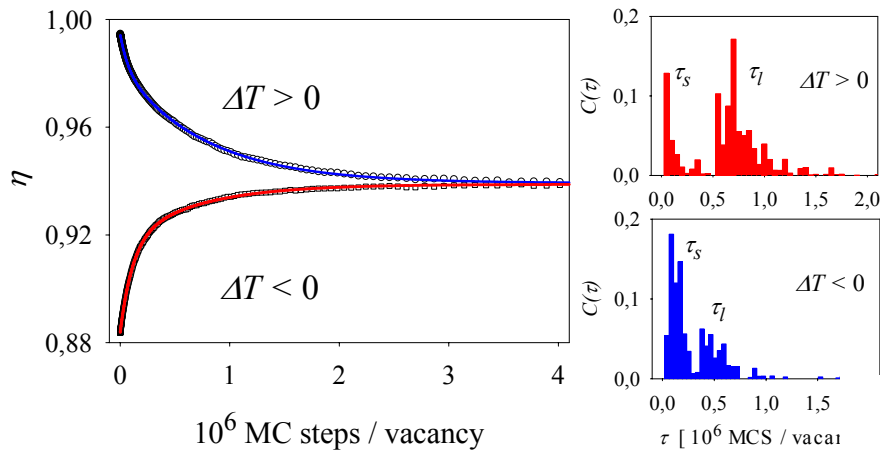
# MC simulations:

P. Oramus, R. Kozubski, V. Pierron-Bohnes,  
M.C. Cadeville, W. Pfeiler, *Phys.Rev.B* **63**, 174109, (2001).

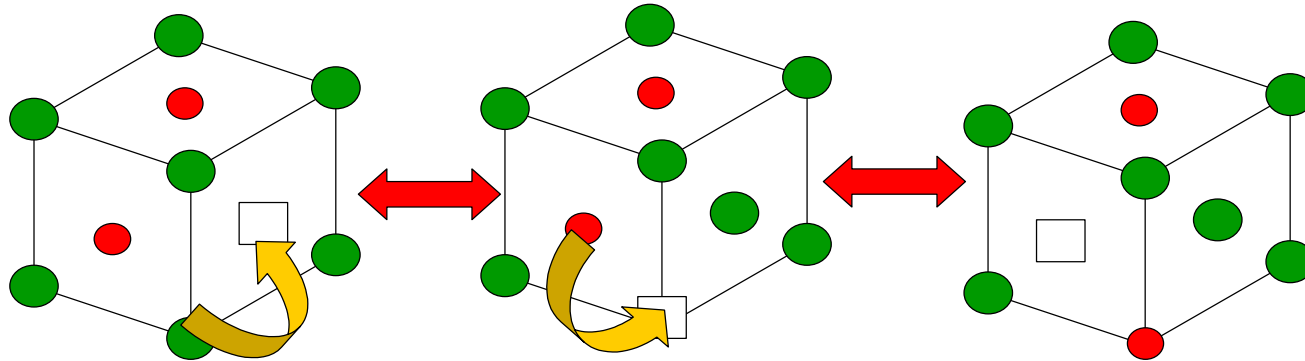
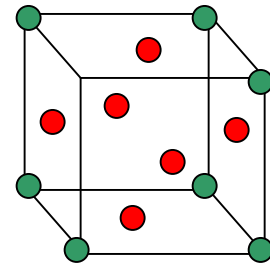
$A_3B$  ( $Ni_3Al$ )



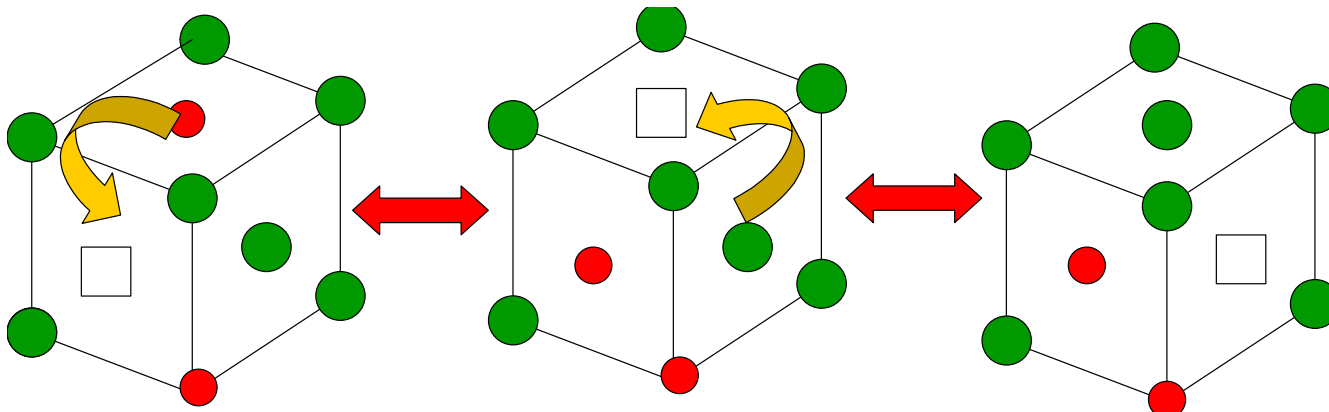
Laplace  
transforms



# ORIGIN OF TWO TIME SCALES IN „ORDER-ORDER” KINETICS IN $L1_2$ -ORDERED $A_3B$

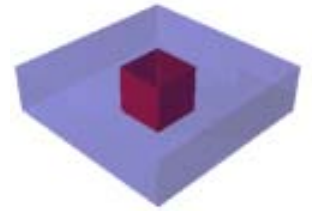


**Fast process:**  
**APC** saturates  
earlier than  $\eta$

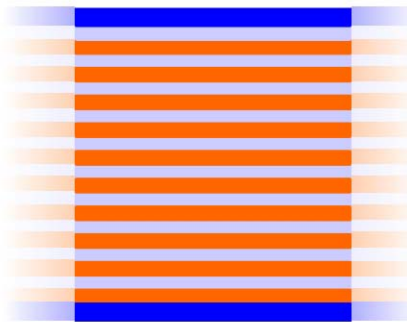
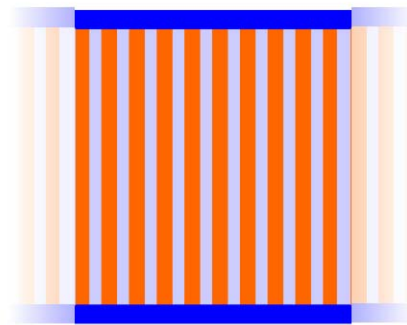
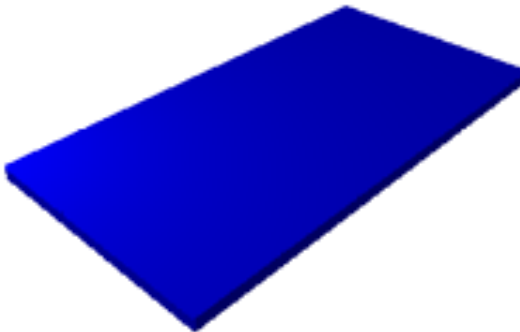
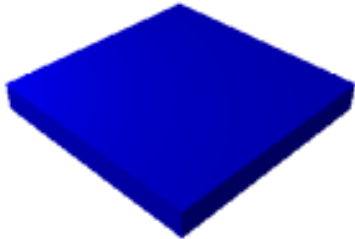
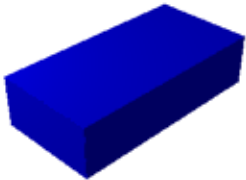



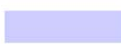


**Slow process:**  
Further change  
of  $\eta$  after  
decreasing **APC**  
by **B-antisite**  
diffusion

# Simulations of FePt thin films



## Sample Geometry

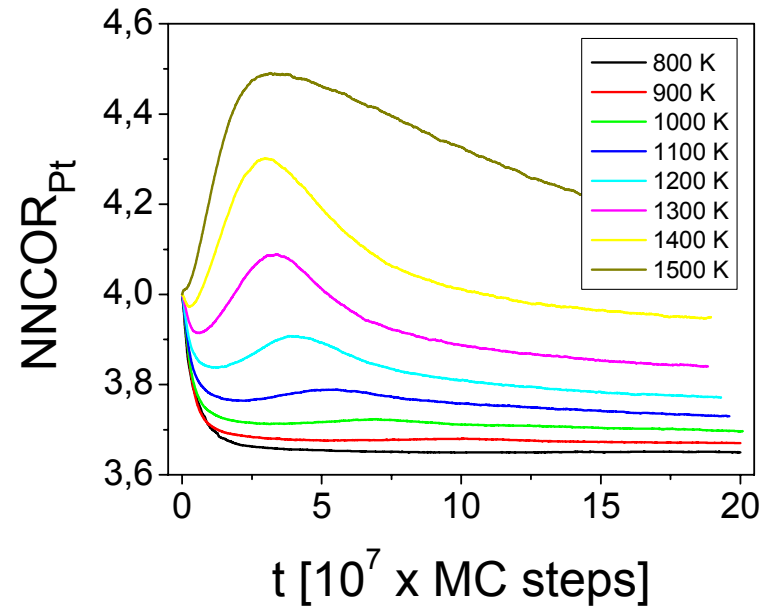
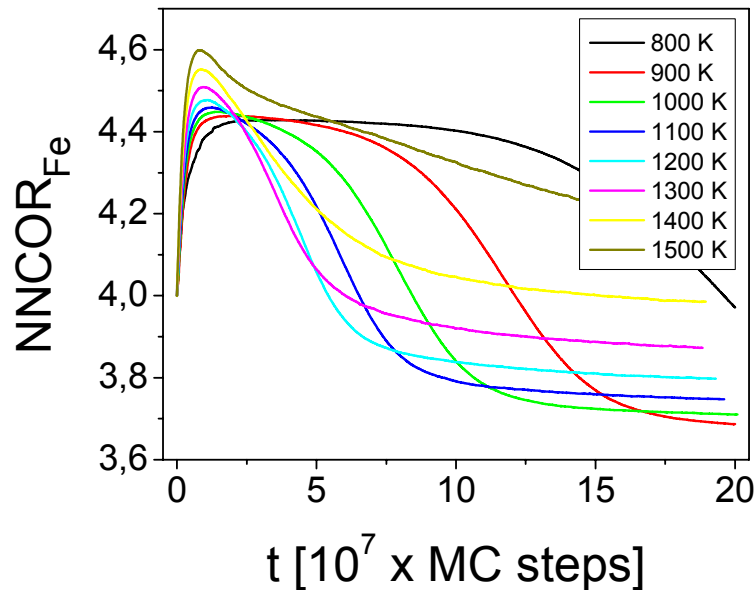
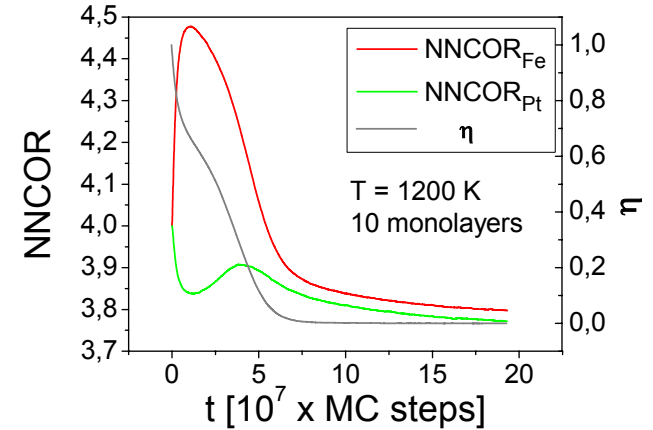
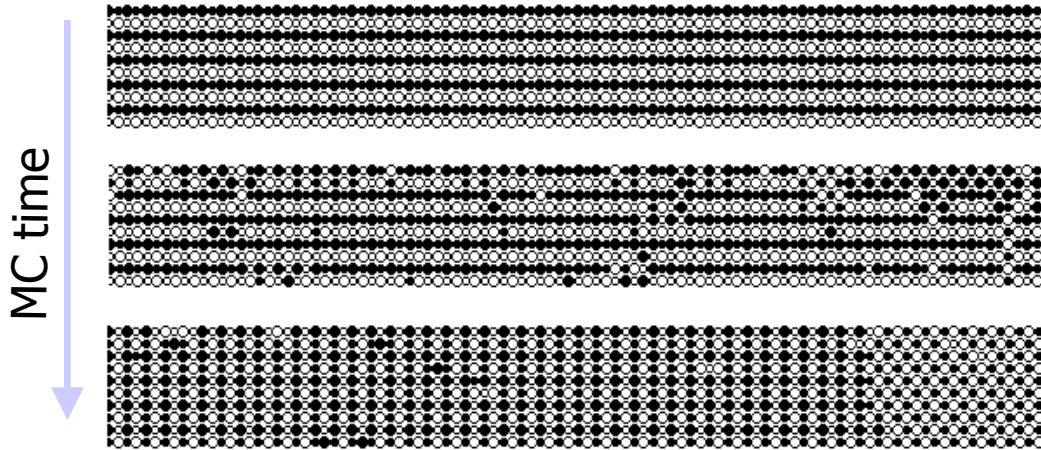


-  - Fe monolayer
-  - Pt monolayer
-  - Free surface
-  - Periodic boundary conditions

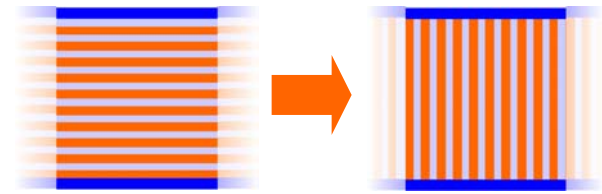
# Results - free surfaces parallel to monoatomic planes



M. Kozłowski, R. Kozubski, V. Pierron-Bohnes, W. Pfeiler, *Comput.Mater.Sci.* **33**, 287, (2005).



# Reorganization of the superstructure



## Sample:

40 x 40 x 40 unit cells

free surfaces in x direction

## Picture:

$t = 50 * 10^7$  MC steps

(0 40 0) (bigger dots)

(0 41 0) (smaller dots)

○ - Pt atoms

● - Fe atoms

